

Grado en Ingeniería

Further Mathematics. List of exercises.

Chapter 3: Curves and surfaces

1) Consider the parameterized surface given by

$$X : \mathbb{R}^2 \rightarrow \mathbb{R}^3 \\ X(u, v) = (u, v, u^2, v^2) \cdot$$

Determine the point wht the biggest Gauss curvature.

2) Consider the parameterized surface given by

$$X : [0, 2\pi) \times \mathbb{R} \rightarrow \mathbb{R}^3 \\ X(u, v) = (v^2 \cos(u), v^2 \sin(u), v) \cdot$$

Determine the point for which the Gauss curvature is negative.

3) Consider the parameterized surface given by

$$X : [0, 2\pi) \times \mathbb{R} \rightarrow \mathbb{R}^3 \\ X(u, v) = (v \cos(u), v \sin(u), v) \cdot$$

Compute the Gauss and mean curvature.

Remark: To compute the Gauss curvature we need first to obtain the unit norm vector (shape operator) given by

$$n(u, v) = \frac{X_u(u, v) \times X_v(u, v)}{\|X_u(u, v) \times X_v(u, v)\|}$$

Then we know that the partial derivatives of $n(u, v)$ lye on the tangent plane at the corresponding point $X(u, v)$ that is generated by mean of the two tangent vectors $X_u(u, v)$, $X_v(u, v)$. Therefore:

$$n_u(u, v) \stackrel{\text{not}}{=} \frac{\partial n}{\partial u}(u, v) = \alpha_u X_u(u, v) + \beta_u X_v(u, v) \\ n_v(u, v) \stackrel{\text{not}}{=} \frac{\partial n}{\partial v}(u, v) = \alpha_v X_u(u, v) + \beta_v X_v(u, v)$$

Then the Weingarten transformation is

$$dn(u, v) = \begin{pmatrix} \alpha_u & \alpha_v \\ \beta_u & \beta_v \end{pmatrix}$$

and then we have

- The Gauss curvature at $X(u, v)$ is $K(u, v) = \det(dn(u, v)) = \alpha_u \beta_v - \alpha_v \beta_u$,
- The mean curvature at $X(u, v)$ is $H(u, v) = \frac{1}{2} \text{trace}(dn(u, v)) = \frac{1}{2} (\alpha_u + \beta_u)$.